HEBI ROBOTICS

R-Series Gripper

Wire Actuated 2-Finger Gripper

Assembly Instructions

General Warnings and Cautions

Danger (May cause serious injury or death)

- Keep water, flammables, solvents and other liquids clear from **unsealed** actuator.
- Keep fingers away from moving parts during operation.
- Cut power immediately if actuator emits strange odors or smoke.
- Keep actuator out of reach of children.

Warning (May cause injury or damage to actuator)

- Do not expose the actuator to permanent and strong magnetic fields.
- Do not force screws into the bottom of the actuator. R8 = 8mm Tap Depth
- Use provided hardware with accessories and hand tighten as needed.
- Attempts to disassemble actuator will void the warranty and may cause permanent damage.

Sealing (R-Series Actuators are IP67 when properly used)

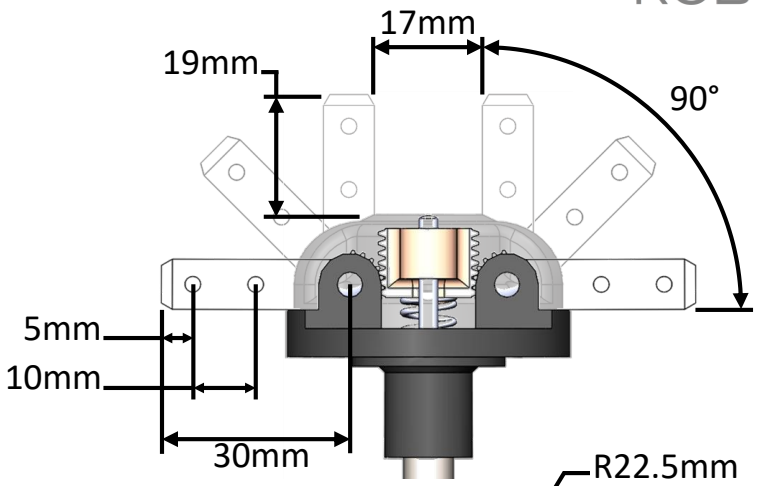
- Please refer to all online documentation for proper sealing techniques of the actuator.

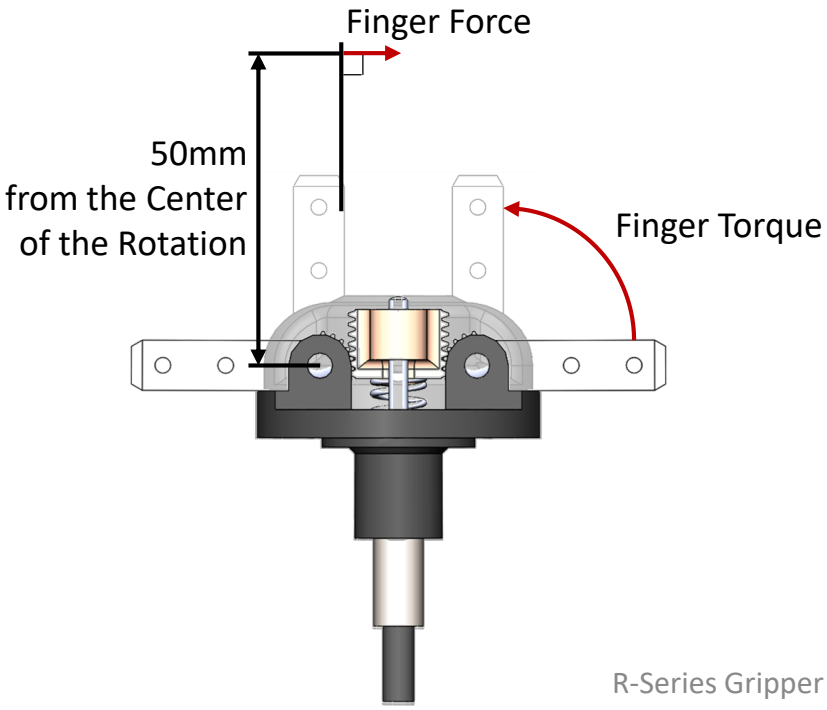
For more information please visit: ***docs.hebi.us***

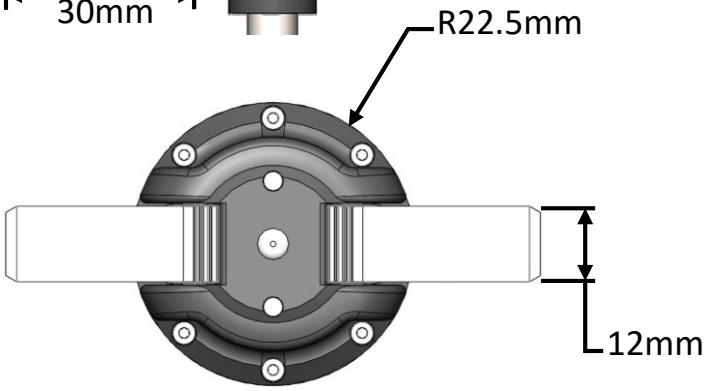
Technical Specifications

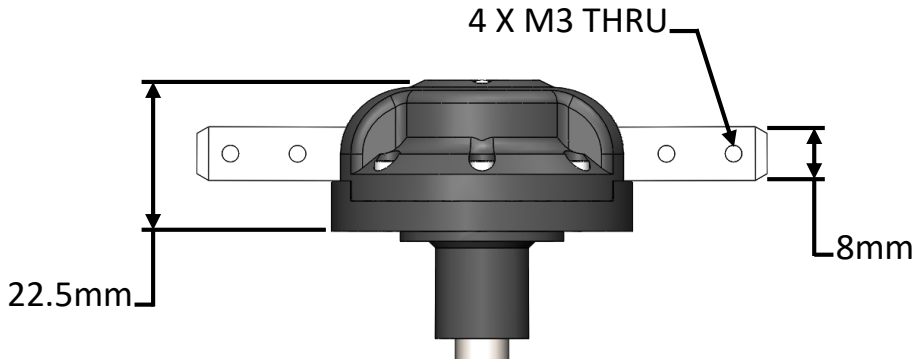
Spool Module	Max Finger Torque	Max Finger Force at 50mm
R8-3	0.4 Nm	8 N
R8-9**	1.1 Nm	23 N
R8-16	2.0 Nm	40 N

* Values assume a symmetric two-finger grasp
** Default Module

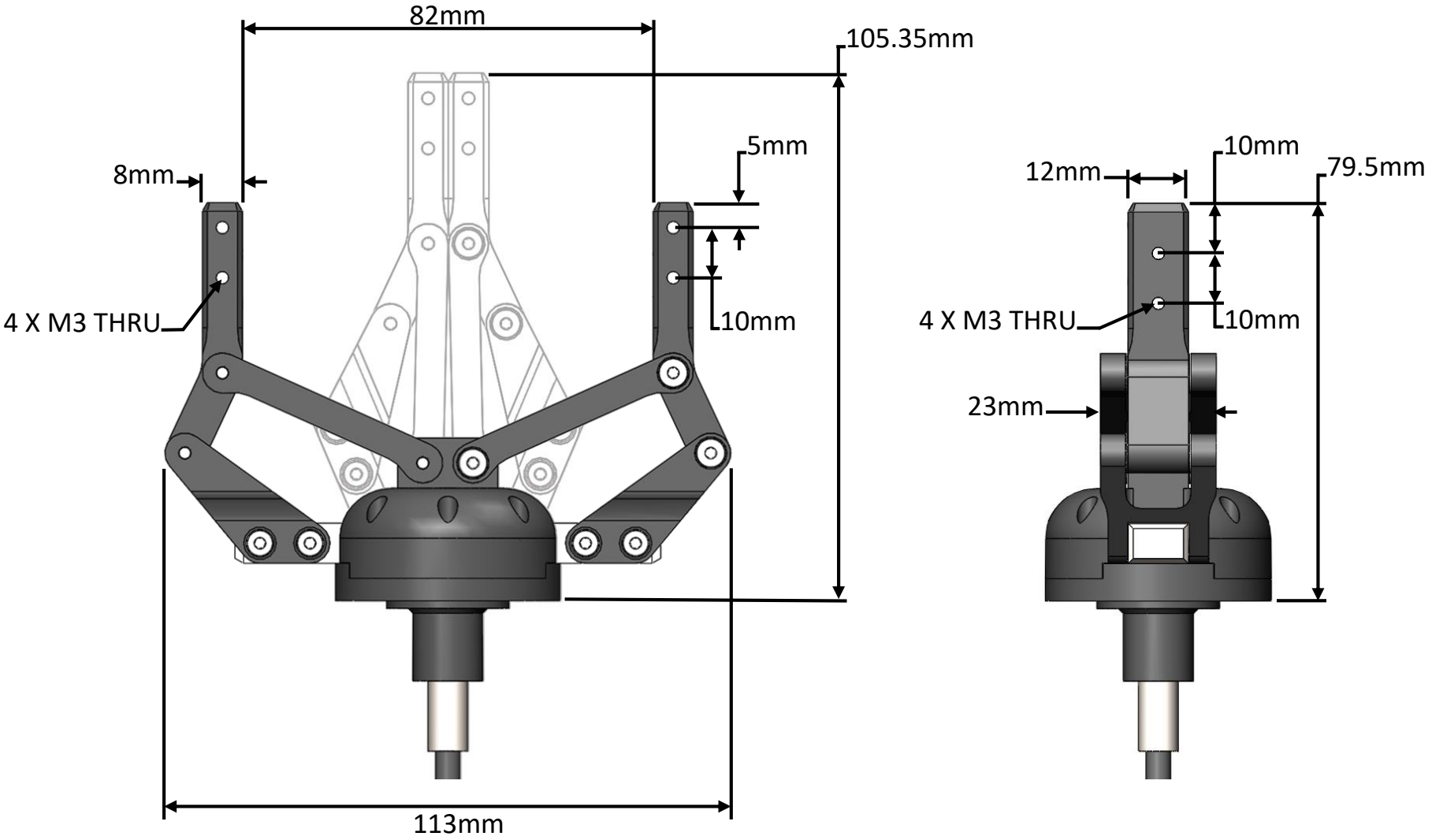








Technical Specifications



Bill of Materials

Default Configuration

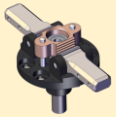
1 x
R8-3
Right Angle Connector

1 x
R8-9
Straight Connector

1 x
PM-2292-01
Spool

1 x
PM-2546-01
R-Series Spool Housing

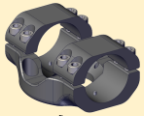
1 x
PM-2290-01
Cable Clamp



1 x
A-2293-01
Gripper Assembly

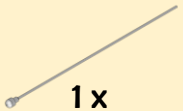
1 x
PM-2343-01
Gripper Cover
(part of A-2055-01)

1 x
A-2143-02
Parallel Linkage Add-on



1 x
A-2224-01

1 x
PM-2222-01
Cable Housing Adapter
(part of A-2055-01)

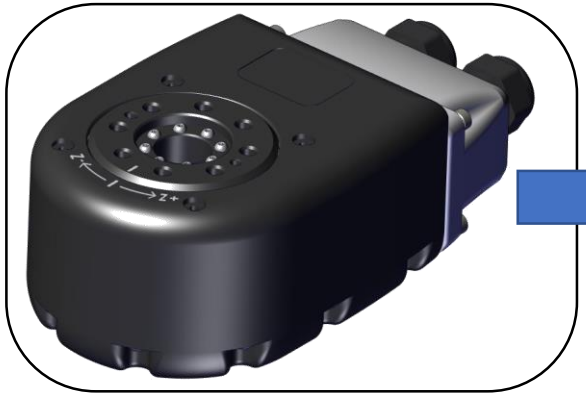


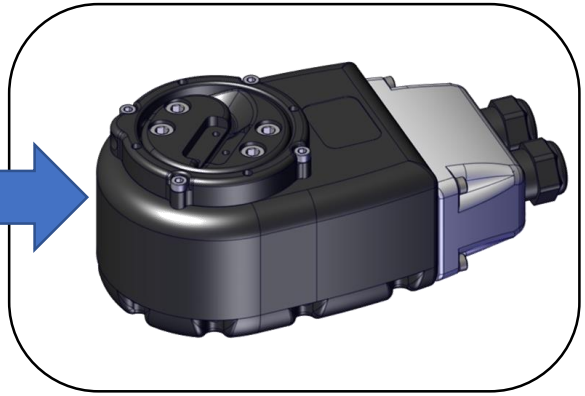
1 x
PP-2239-01
Cable

1 x
PP-2240-01
Cable Housing
(Standard Road Bike Brake Cable Set)

1 x
PP-2241-01
Cable Housing End Cap

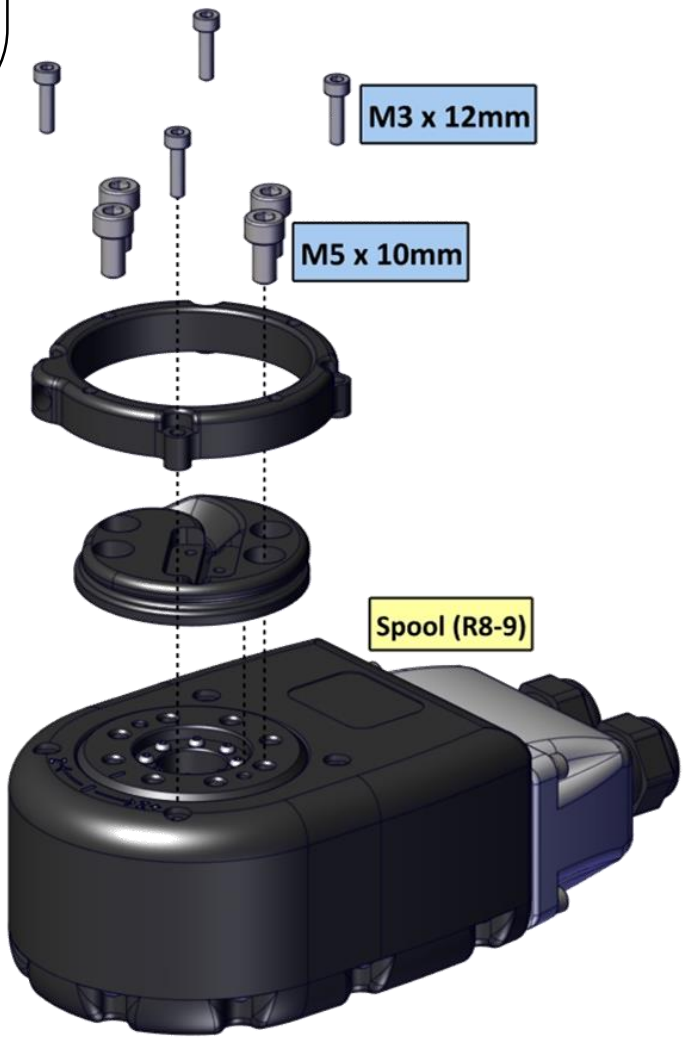
R-Series Actuators sold separately
Fasteners included, not shown

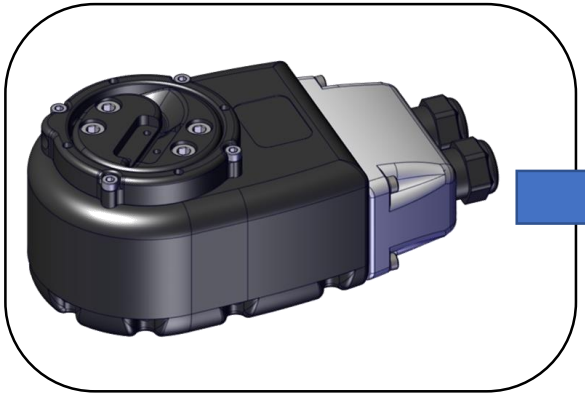


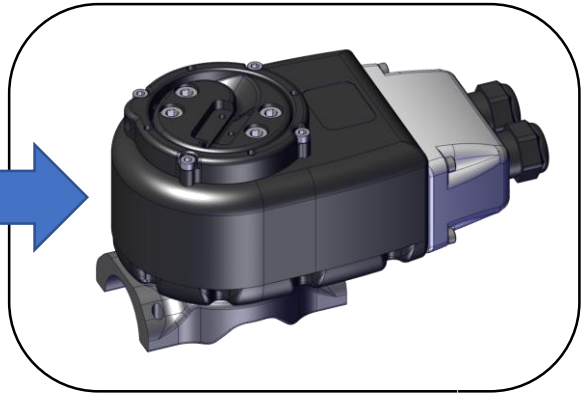


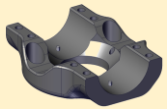
1 x
PM-2292-01
Spool

1 x
PM-2546-01
R-Series Spool Housing





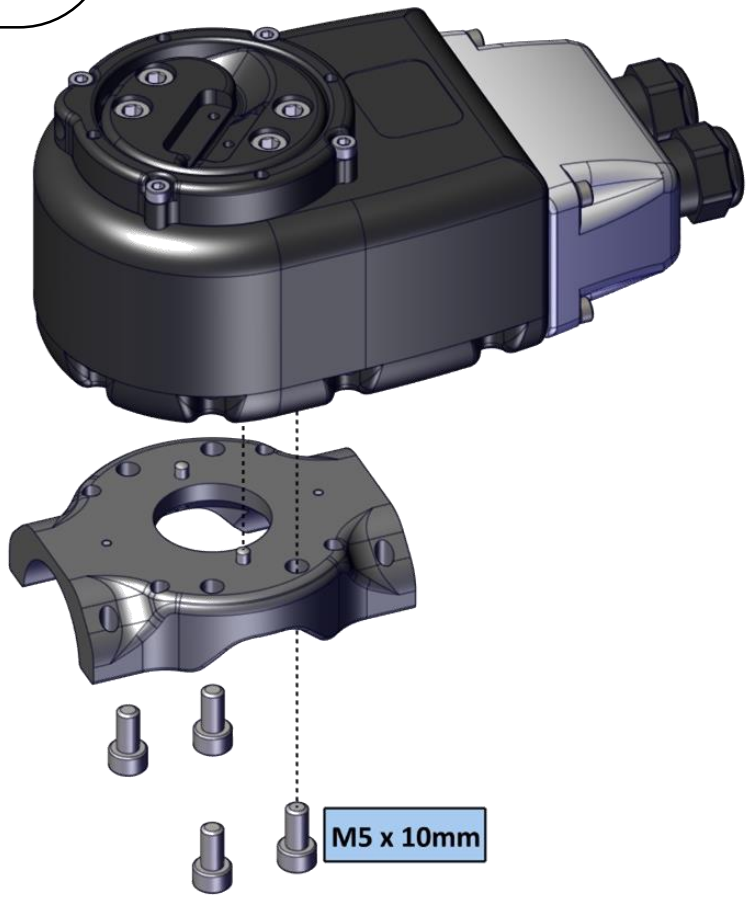


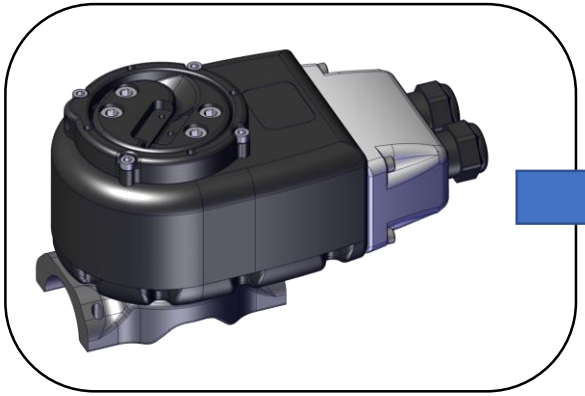


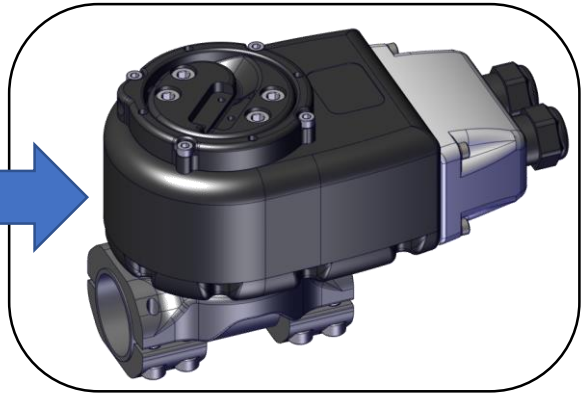
1 x

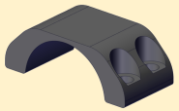
PM-2519-01

Housing Mid-Tube Mount

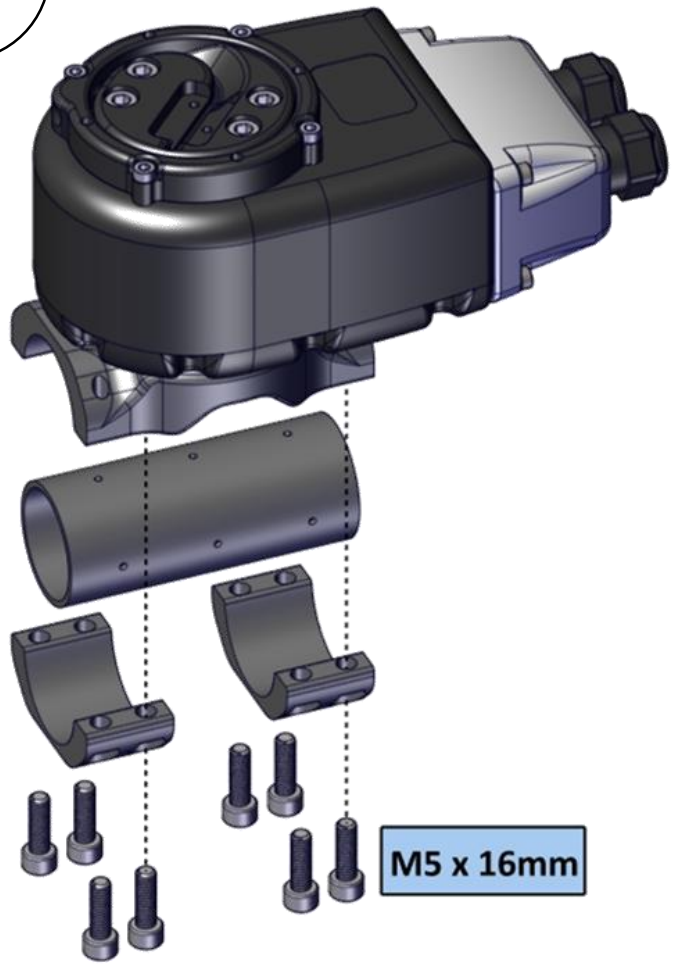


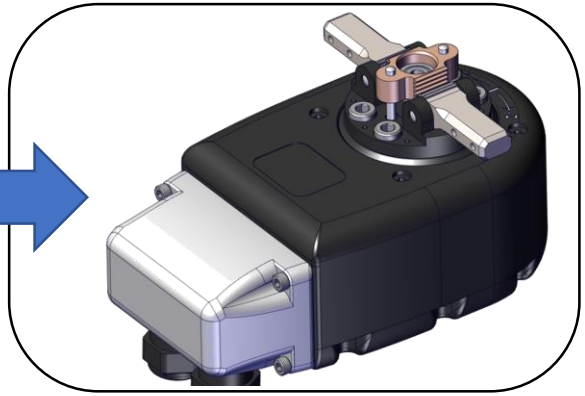


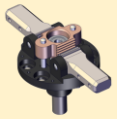




2 x
PM-2148-02
Tube Clamp

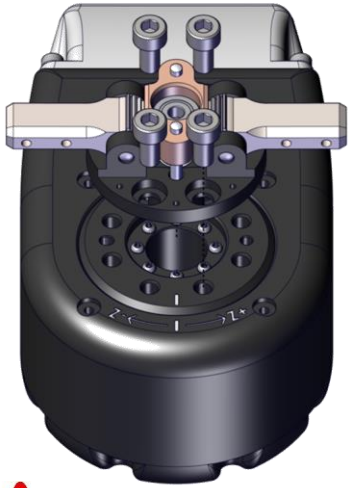




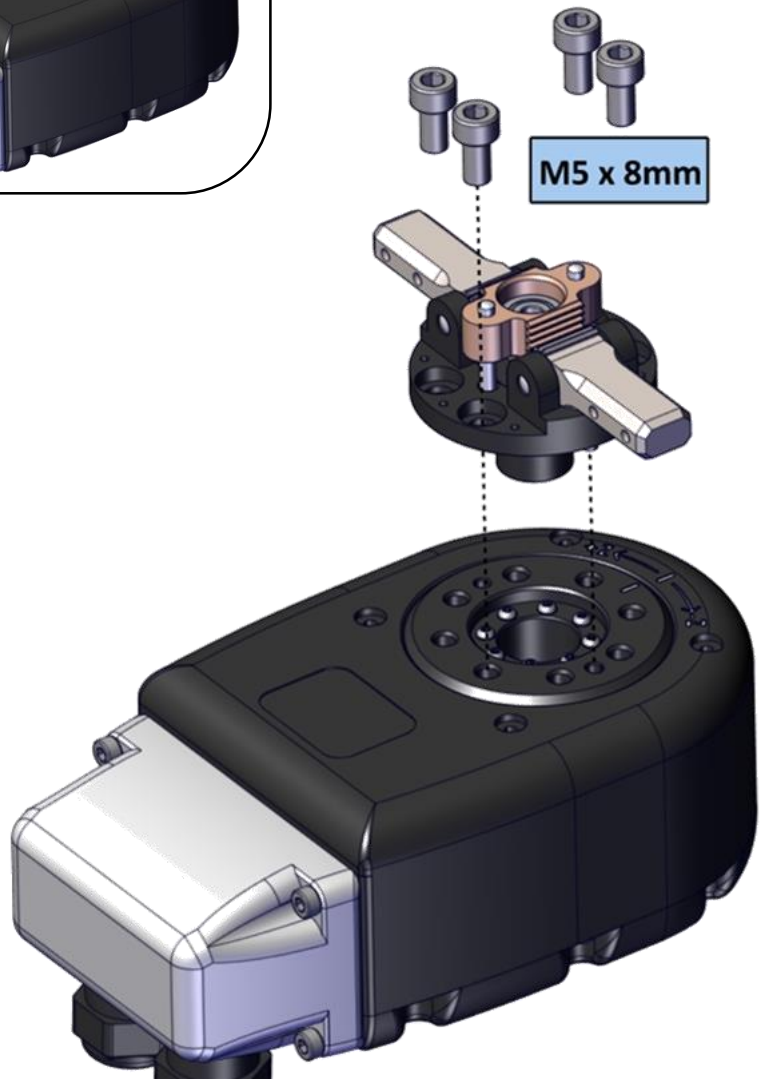


1 x
A-2293-01
Gripper Assembly

1 x
R8-3
Right Angle Connector

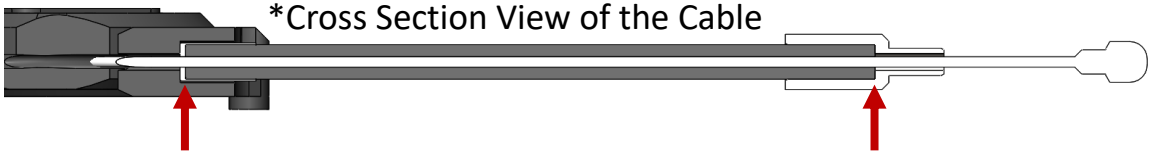


Align with actuator output hub tick mark
(Fingers perpendicular to the tick mark)

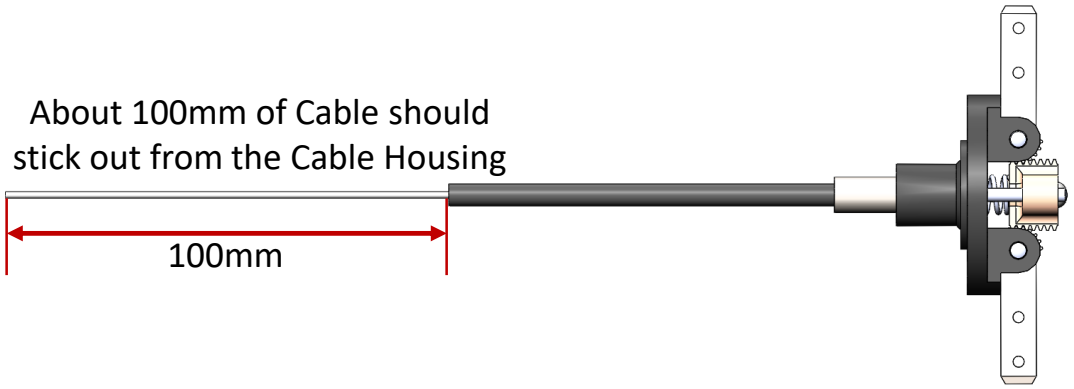


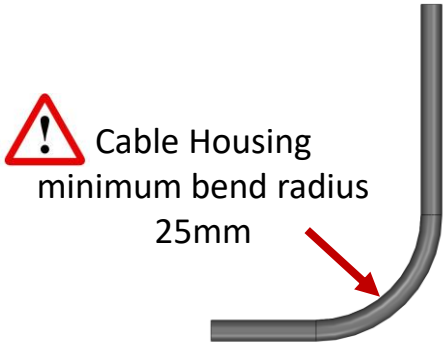
Running the Cable Through

- Make sure to use a Standard Road Bike Brake Cable.
- Run the cable to fit your system.
- Run both the cable and the cable housing before cutting them to ensure that the cable is long enough.
- Cut the cable housing first, and then cut the cable.

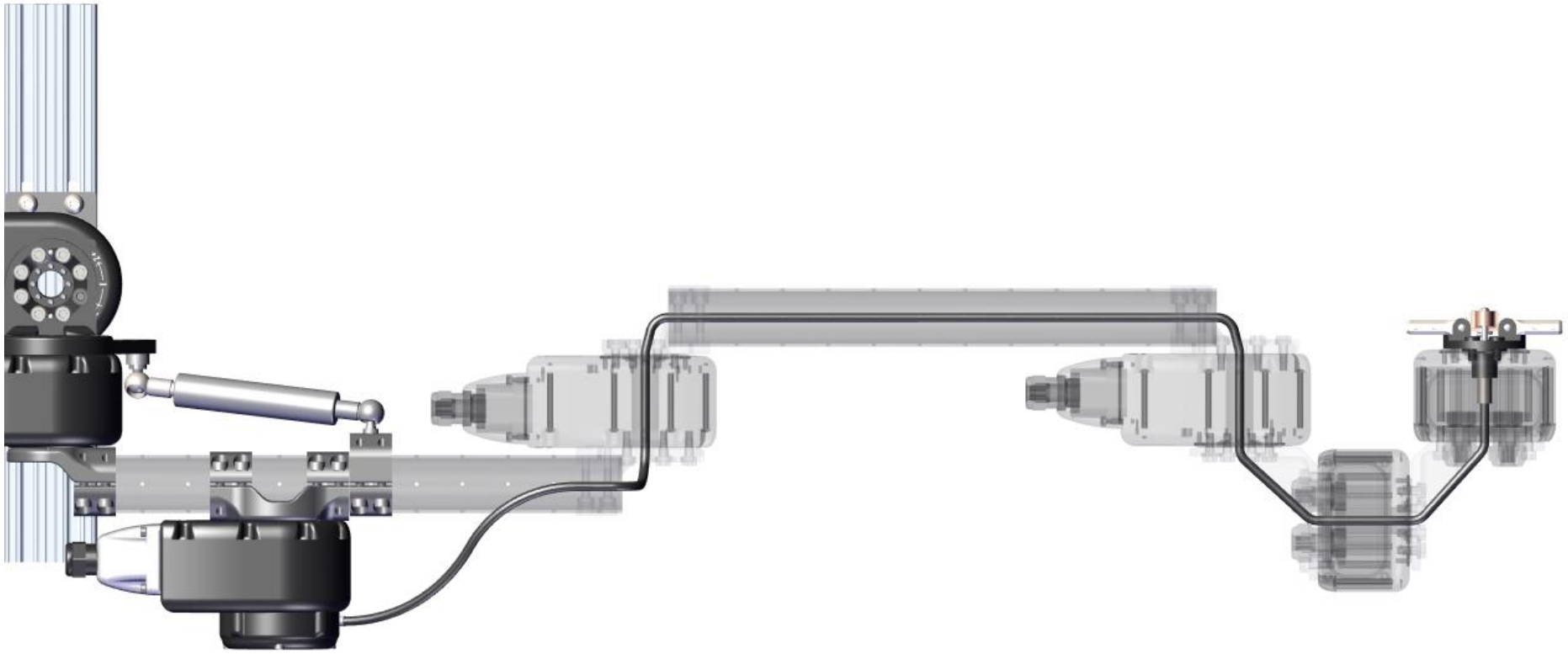


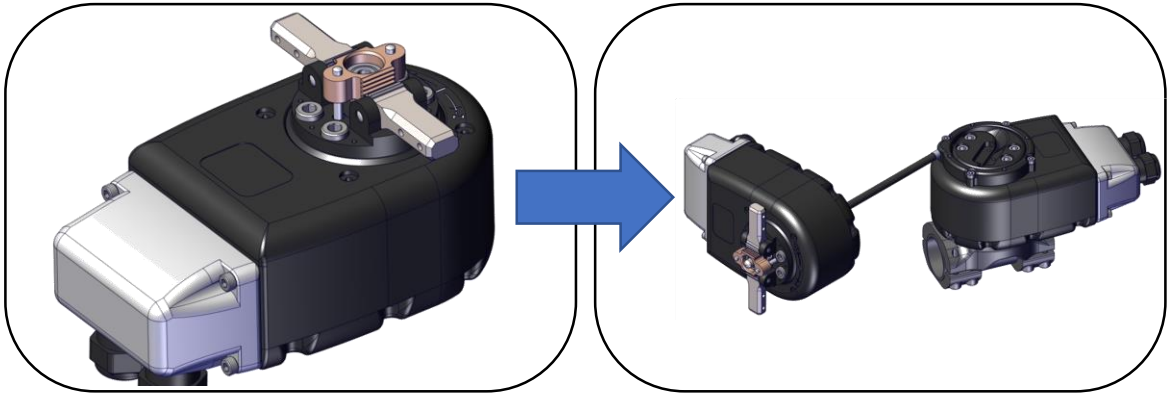
Make sure that the Cable Housing is long enough to be fully inserted into the Housing End Cap and the Housing Adapter

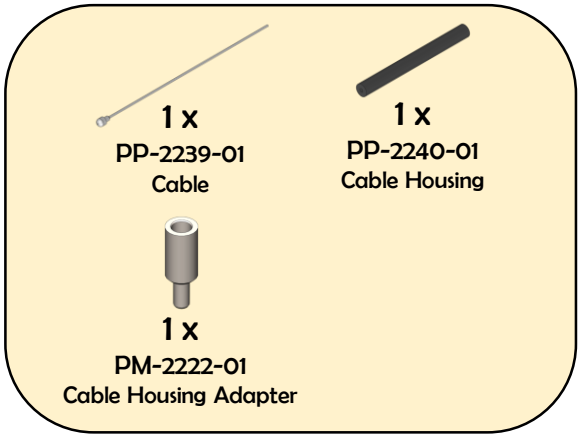


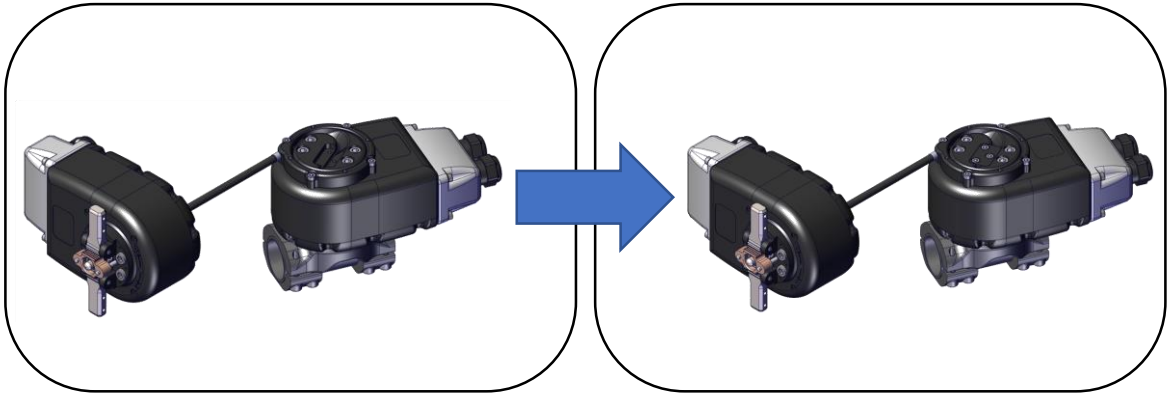


Cable Routing Example (6-Dof Arm)



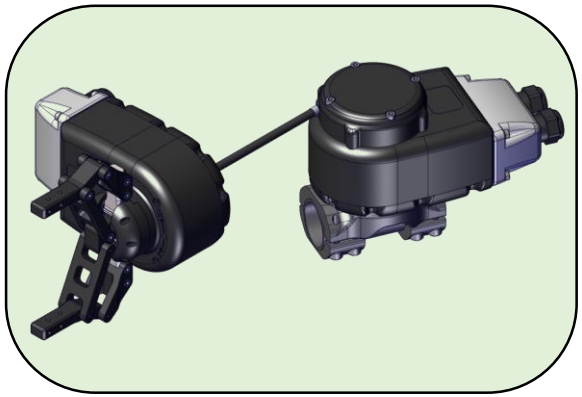



1 x
PP-2239-01
Cable
1 x
PP-2240-01
Cable Housing
1 x
PM-2222-01
Cable Housing Adapter



1 x
PM-2290-01
Cable Clamp

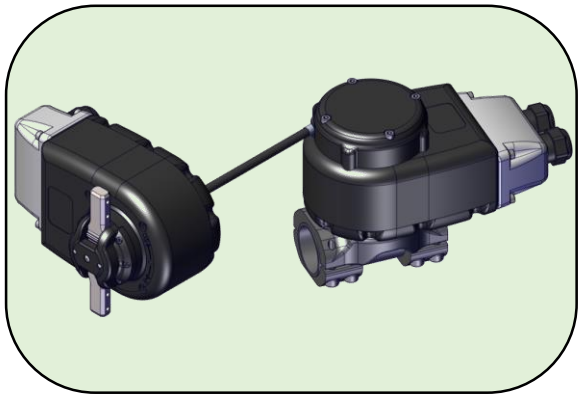
Do NOT operate the gripper at this state. The pins at the pivot of the fingers will fall out.



1 x

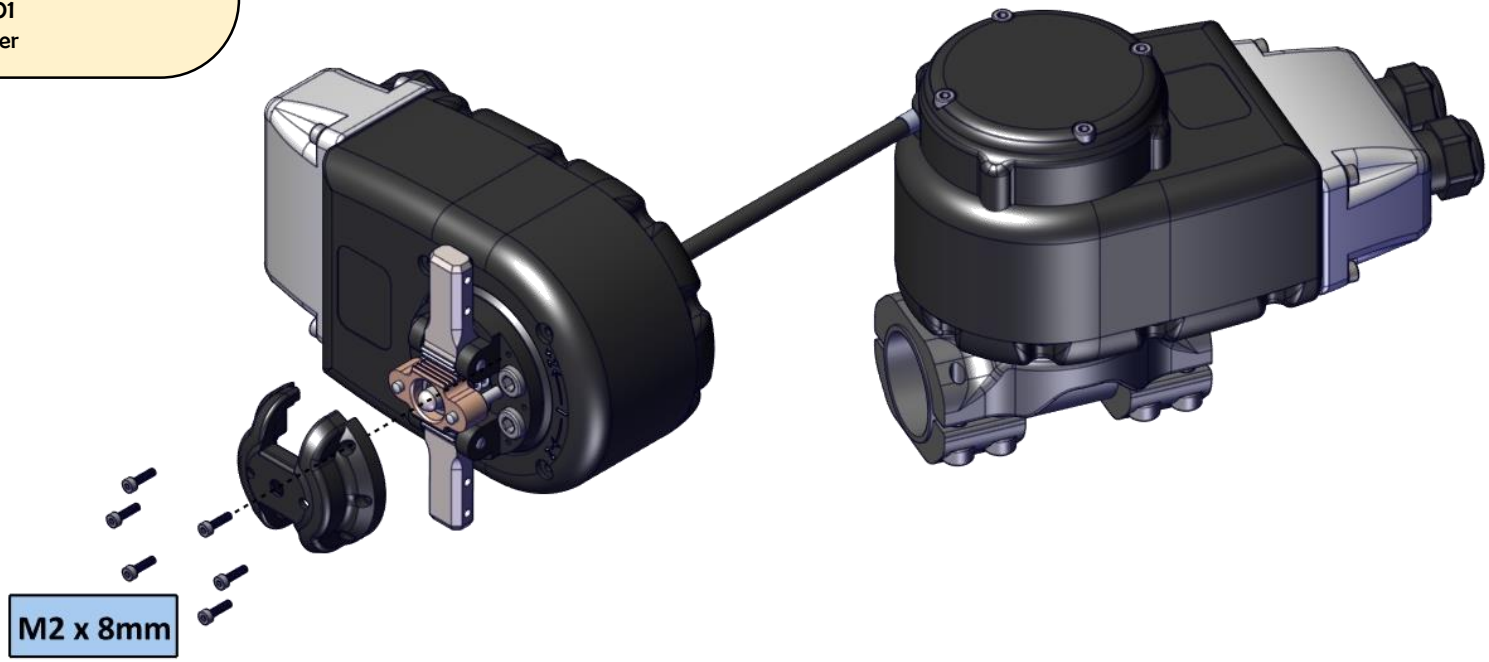
A-2143-02

Parallel Linkage Add-on



Use PM-2343-01 when the parallel linkage is not needed.

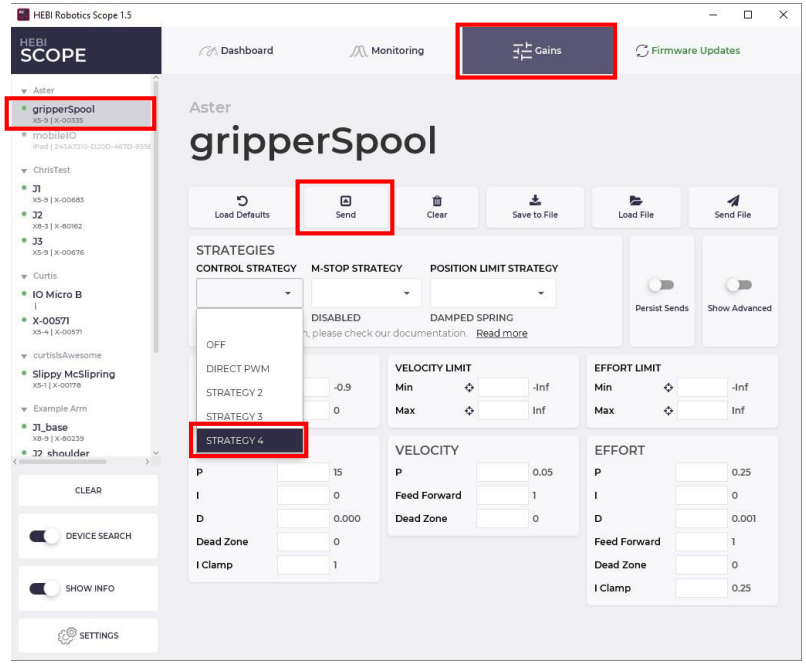
1 x
PM-2343-01
Gripper Cover



Initializing the Spool, pt. 1

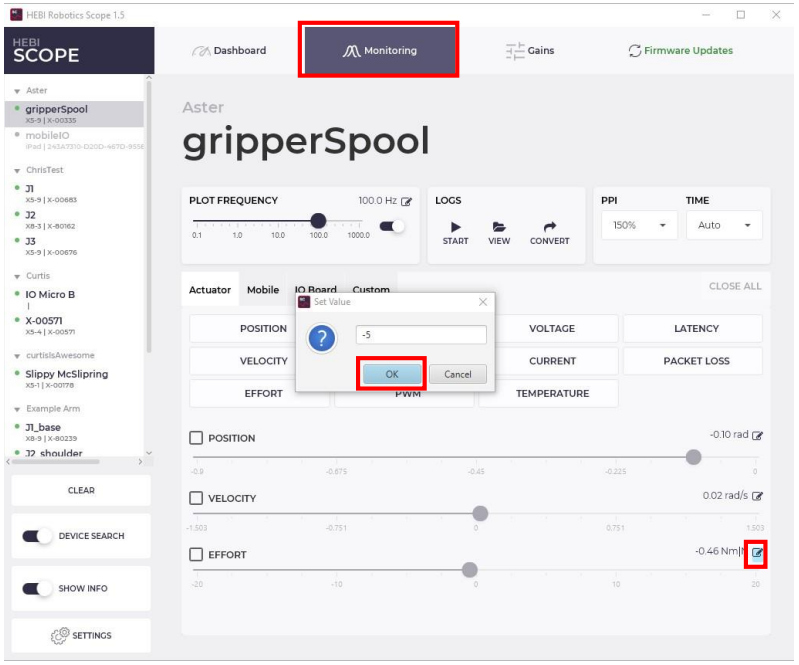
I. Connect the Spool Module into the network, and turn it on

II. Open HEBI Scope GUI



III. Set the Strategy of the Spool Module to "STRATEGY_4"

1. Click on your Spool Module
2. Go to "Gains" tab
3. Use the Control Strategy drop down menu to select a Suitable Strategy for your Application
4. Click "Send"

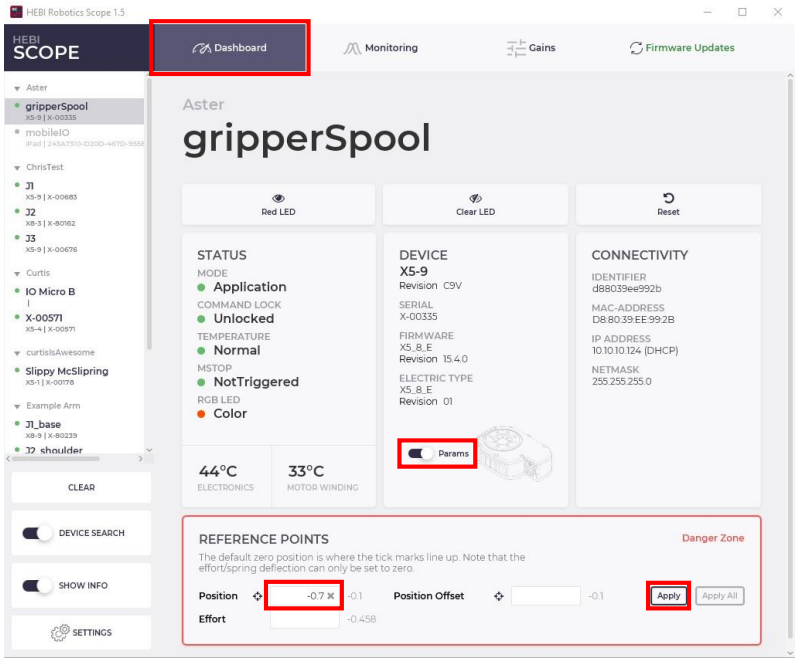


IV. Command the Effort to -5 Nm

1. Go to "Monitoring" tab
2. Click the "Target Button" for the Effort
3. Type "-5" and Click "OK"

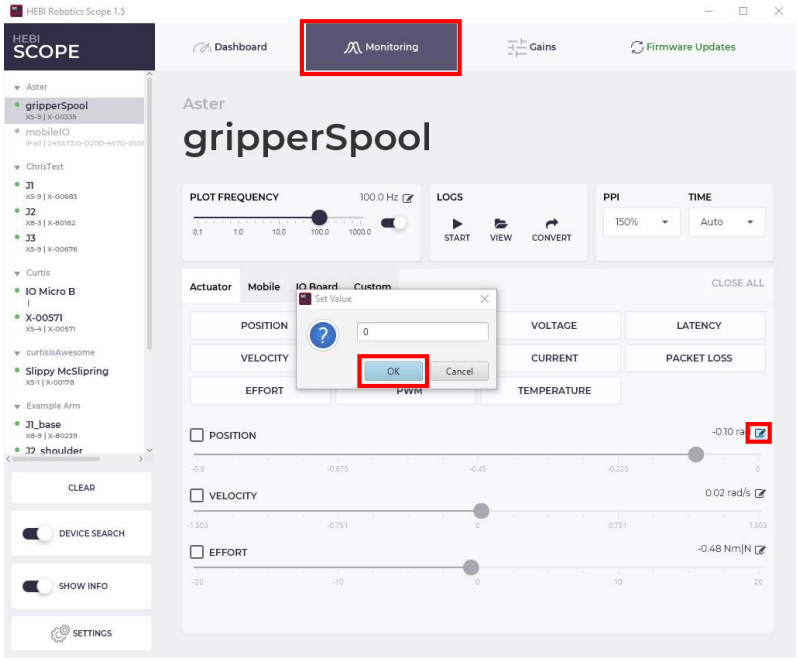
The Spool will wind the Cable and close the Fingers.

Initializing the Spool , pt. 2



V. While Commanding the Effort, set the current position to “-0.7”

1. Go to “Dashboard” tab
2. Toggle “Params” as shown
3. Type “-0.7” for Position
4. Click “Apply”



VI. Stop commanding the effort, and command the position to 0.

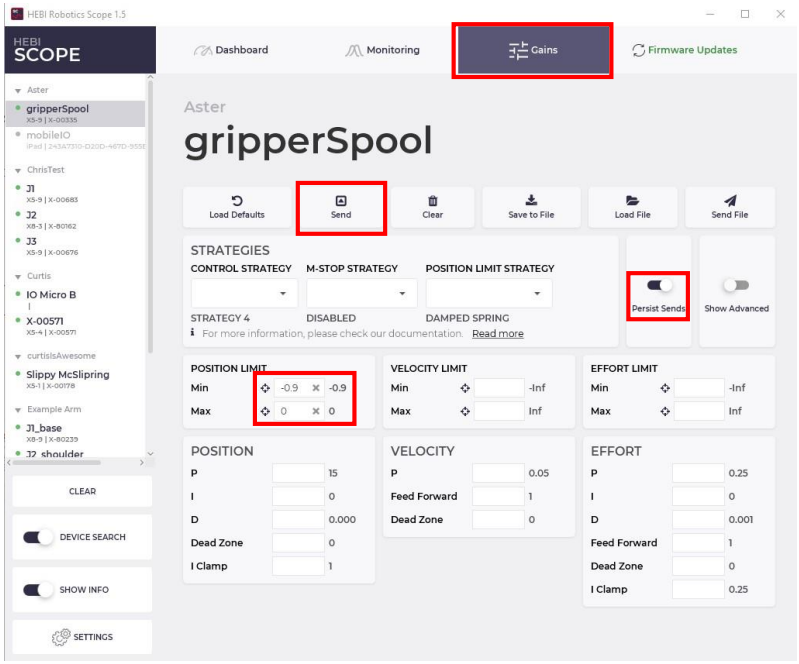
1. Go to “Monitoring” tab
2. Click the “Target Button” for Position
3. Type “0” and Click “OK”

The Spool will unwind the Cable and open the Fingers.

To close the gripper, turn the spool clockwise.

To open the gripper, command the spool to zero position.

Initializing the Spool, , pt. 3



VII. Set Safety Limits for the Spool

1. Go to “Gains” tab
2. Type “-0.9” for Min Position
3. Type “0” for Max Position
4. Toggle “Persist Sends” as shown
5. Click “Send”

If the Safety Limits are not set, the spool can turn to a position greater than zero, and break the cable.

To close the gripper, turn the spool clockwise (negative effort).

To open the gripper, turn the spool counter-clockwise (positive effort)

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